

#### TCS Software Preliminary Design Review

#### Top Level Design Section 1

Feb 1998

NAVAL SURFACE WARFARE CENTER
DAHLGREN DIVISION



#### Agenda

- PDR Part I Review
- Operational Model
- Top Level Design
  - Section 1: CSCIs Overview
  - Section 2: DCM CSCIs
  - Section 3: RTP CSCI
  - Section 4: DataServer CSCI
  - Section 5: DII CSCI
  - Section 6: Route & Payload Planner CSCI
  - Section 7: Common AV & Payload CSCI



# CSCIs Top Level Design Overview

Interfaces

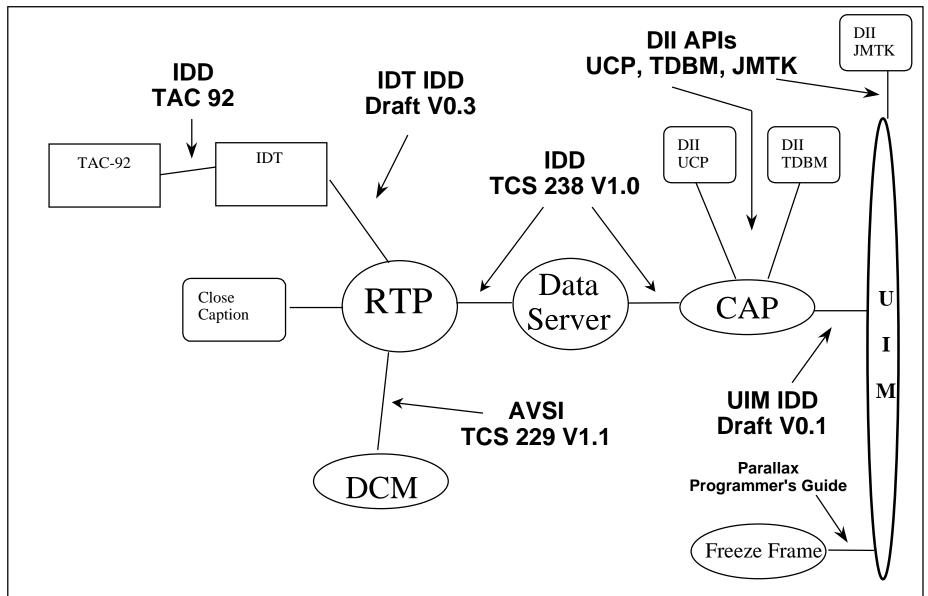
Disk Storage

Data Flow

Run States



#### <u>Interfaces</u>





#### Disk Storage Utilization

OS & Files

464.6 MBytes

• DII Core

**245.1** MBytes

• DII JMTK

62.0 MBytes

DII Comms

108.5 MBytes

• TCS

**572.0** MBytes

- CAP

20.3 MBytes

- RPP

551.7 Mbytes

-DS

1.6 MBytes

- RTP

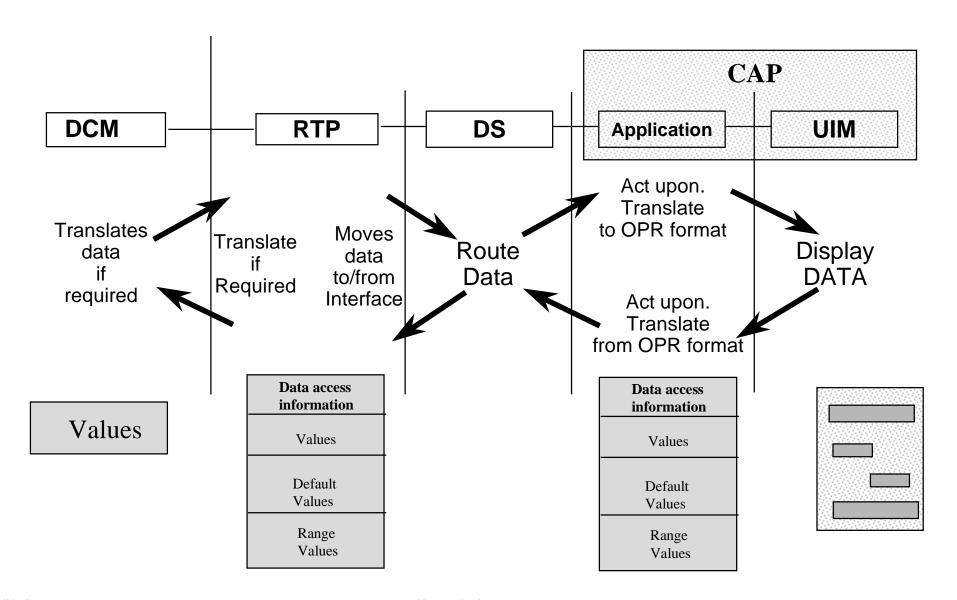
1.9 Mbytes



#### **Data Flow**



#### TCS CSCIs High Level Data Flow





#### **AVSI Messages**

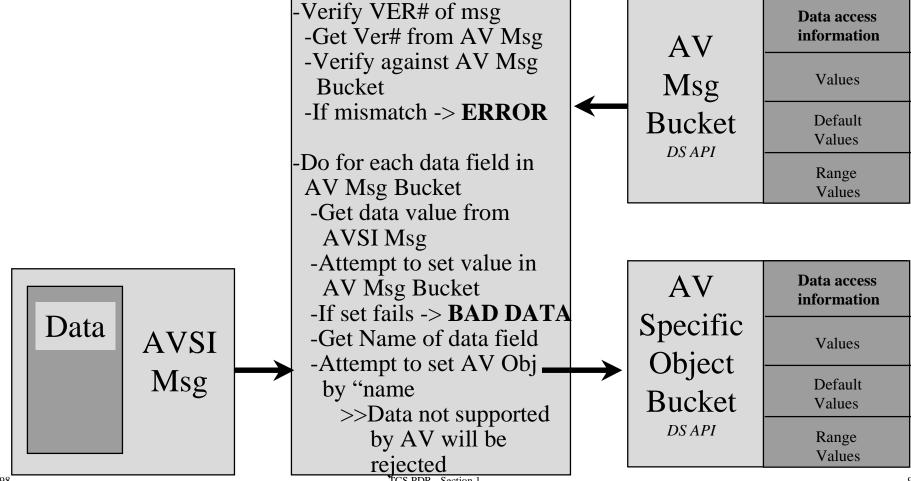
- For every AVSI Message
  - There is a corresponding but AV specific DataServer Bucket
- AVSI Messages are built as a composite/superset of data supported by the AVs
  - Unsupported fields are zeroed
- These composite messages are then converted to internal AV specific version of the message
  - Unsupported fields are not in the bucket



#### **AVSI Mapping to TCS Buckets**

#### •Initialization:

- •Create AV Msg Bucket
- •Create AV Specific Object Bucket
- •Populate AV Specific Object with default values from AV Msg Bucket



02/03/98



## Schema Example AVSI Version of AV Position Status

```
AV Position Status
   # Version and configuration information
  Version "$Id$";
  Config COMMON GROUP;
   # Constant telling which message this is
  Message_ID: const integer, 1, "Message ID";
  # Constant telling the IDD version for the message definition
  Message_Version: const integer, COMMON_VERSION, "Message Version";
  # Type of AV:
  AV Type: integer, AV COMMON, 1 .. AV TYPE LIMIT, "Type of AV";
   # Air Vehicle Tail number (13 characters long, last char is NULL)
 AV_Tail_Number: string[13], "UAV000", , "Tail Number";
             \circ
             0
 # GPS Time fields: weeks, seconds, and nanoseconds. Note: GPS week
 # will roll over to 0 in August 1999.
 AV GPS Time Week:
                       integer, 0, 0 .. 1023, "weeks", "GPS Time";
 AV_GPS_Time_Second: integer, 0, 0 ... 604799, "sec", "GPS_Time";
 AV_GPS_Time_Ns:
                       integer, 0, 0 .. 999999999, "ns", "GPS Time";
 # Altitude as sensed by the barometer
 AV Baro Altitude: real, 0.0, AV ALT MIN .. AV ALT MAX, "ft",
     "Barometric Altitude";
 # Altitude as sensed by the radar
 AV Radar Altitude: real, 0.0, AV ALT MIN .. AV ALT MAX, "ft",
     "Radar Altitude";
 # Heading as sensed by the magnetometer
AV Magnetometer Heading: real, 0, [0.0, 360.0), "deg", "Mag Heading
```



## Schema Example Predator's Version of AV Position Status

```
AV Position Status
   # Version and configuration information
  Version "$Id$";
   Config PREDATOR_GROUP;
   # Constant telling which message this is
  Message_ID: const integer, 1, "Message ID";
   # Constant telling the IDD version for the message definition
  Message Version: const integer, PREDATOR VERSION, "Message Version";
   # Type of AV:
  AV Type: const integer, AV PREDATOR, "Type of AV: Predator";
   # Air Vehicle Tail number (13 characters long, last char is NULL)
 AV Tail Number: string[13], "UAV000", , "Tail Number";
   # GPS Time fields: weeks, seconds, and nanoseconds. Note: GPS week
   # will roll over to 0 in August 1999.
                        integer, 0, 0 .. 1023, "weeks", "GPS Time";
  AV GPS Time Week:
  AV GPS Time Second: integer, 0, 0 .. 604799, "sec", "GPS Time";
                        integer, 0, 0 .. 999999999, "ns", "GPS Time";
  AV_GPS_Time_Ns:
   # Altitude as sensed by the barometer
  AV_Baro_Altitude: real, 0.0, -3000 .. 60000, "ft",
      "Barometric Altitude";
   # Altitude as sensed by the radar
  AV Radar Altitude: real, 0.0, AV ALT MIN .. AV ALT MAX, "ft",
      "Radar Altitude";
   # Heading as sensed by the magnetometer
  AV_Magnetometer_Heading: real, 0, [0.0, 360.0), "deg", "Mag
Heading";
```

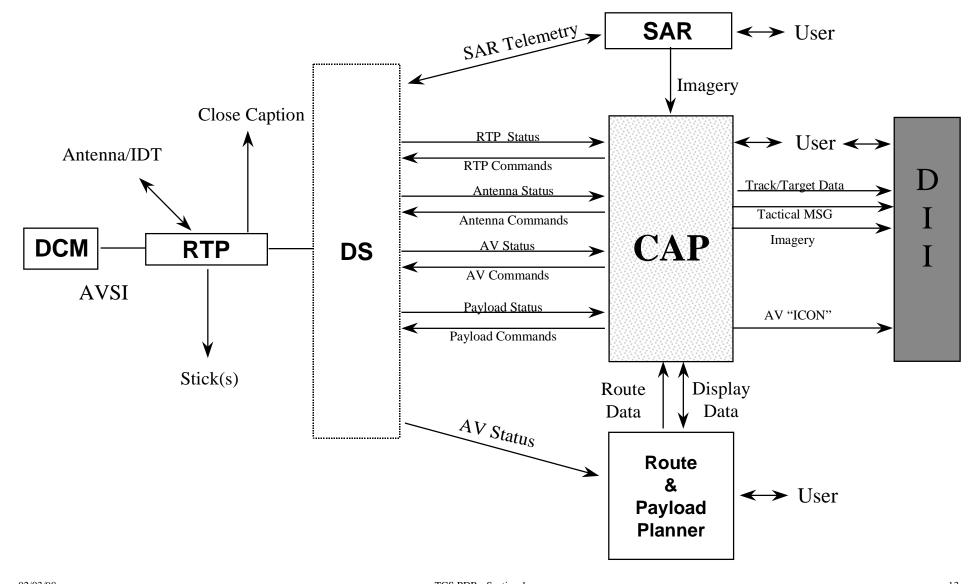


#### TCS Buckets

Downlink (DCM to TCS)	Uplink (TCS to DCM)			
AV Position Status	AV Flight Mode Command			
AV INS Status	AV Flight Envelope Command			
AV GPS Status	AV Lights Command			
AV EOIR Status	TCS Position Uplink			
AV Line of Sight GDT Status	TCS Environmental Data Uplink			
AV Line of Sight ADT Status	EOIR Command			
AV Piston Engine Status	AV Analog Video Command			
AV Fuel Status	AV Waypoint Begin			
AV Electrical System Status	AV Piston Engine Command			
AV Analog Video System Status	AV IFF Command			
AV Lights and Landing Gear Status	AV Fuel System Command			
AV IFF Status	Ground Line of Sight Datalink Command			
AV SAR Status	Airborne Line of Sight Datalink Command			
AV Warning	Airborne SATCOM Datalink Command			
DCM Protocol Error				
DCM Mission Load Acknowledge				
AV Servo Status				



#### TCS CSCIs Data Flow





#### **CSCIs Run States**

Startup
Operations
Shutdown



#### System States

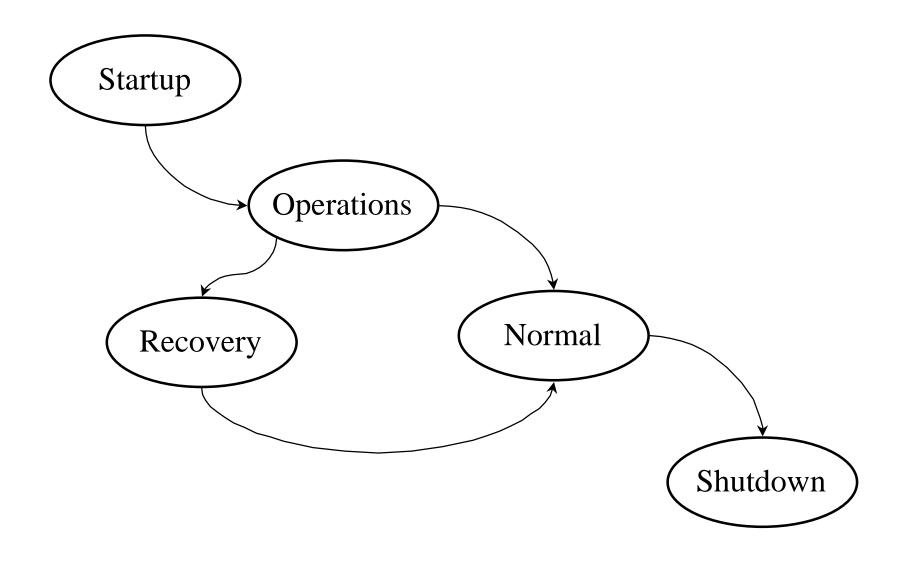
• (SSS014)[SSDD0263]

The TCS Core Functionality CSCIs shall provide and control the TCS states of operation, Startup, Operation, and Shutdown.

- Startup
  - The process of applying power to equipment and the activation of those HWCIs and CSCIs necessary for Operations.
- Operations
  - All HWCIs & CSCIs are in a state ready to accept and process commands
- Shutdown
  - Command from the operator to halt equipment in preparation for power down

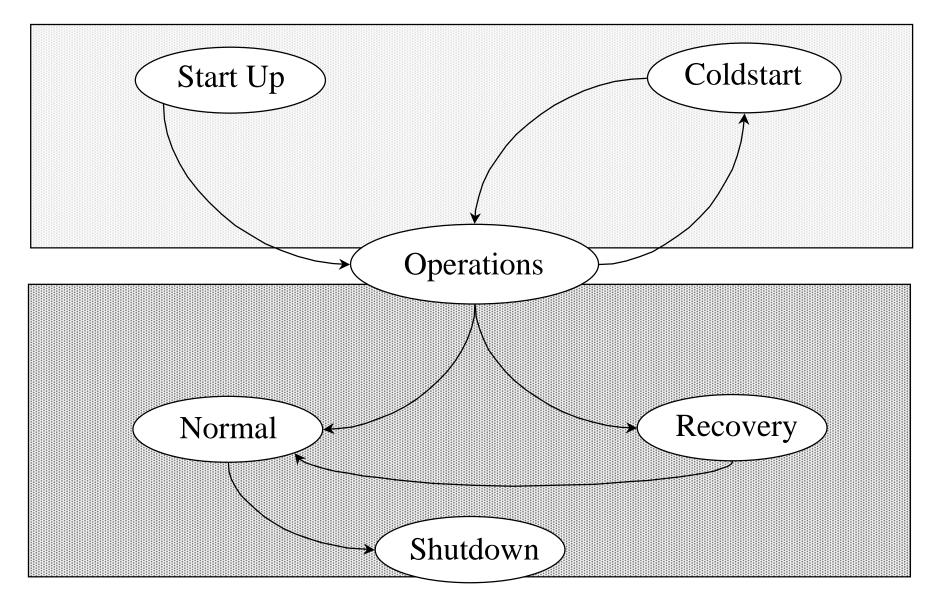


### System States





#### Software States





#### Startup State



#### <u>Startup</u>

- The process of applying power to equipment and the activation of those HWCIs and CSCIs necessary for Operations.
  - Startup is divided into the following substates
    - Coldstart
      - Start up with no configuration data and no state data
      - Manual configuration is required
    - Startup or Normal Startup
      - Start up with configuration data and state data



#### Startup - Coldstart

- Manual Coldstart operations
  - Hardware, Network, OS, DII, & TCS configuration
    - Installation and/or removal of equipment
    - Network setup
      - Routers/Hubs, etc.
    - DII/OS Configuration
      - Network Addresses
      - Host Tables
    - DII Software/Segment Installer
    - DII User Accounts



#### Startup - Coldstart

- Coldstart (Continued)
  - TCS Setup
    - Create/modify a "database" that identifies TCS's hardware assets
    - TCS "power up"
      - Ensure that all equipment as specified in Setup is powered up and operational



#### Startup: DCM(s)

- Auto boot, load, and start DCM CSCI
  - COLDSTART:
    - Same as Normal Mode
  - NORMAL STARTUP:
    - DCM starts and initializes its CSCs.
    - Waits of a connection from RTP.
    - Once connected begin processing commands and make available any downlink data if present.
  - RECOVERY:
    - Same as Normal



#### Startup: RTP

- RT
  - Auto boot, load, and start RTP\_Exec CSC
    - COLDSTART:
      - Wait for RTP configuration data
      - Enter Normal mode when "config" bucket received
    - NORMAL STARTUP:
      - Get RTP configuration data.
      - Start required CSCs.
      - Wait for commands
    - RECOVERY:
      - Same as Normal State



#### Startup: RTP (Continued)

- DS
  - Auto boot, load, and start DataServer CSCI
    - COLDSTART:
      - Same as Normal State
    - NORMAL STARTUP:
      - Start and initialize all CSCs.
      - Read Persistent Storage File if one exists.
        - » Persistent storage is used to save the last valid data set. This data is automatically returned when bucket is re-created by an application
        - » Wait for connections and process commands as they arrive
    - RECOVERY:
      - Same as Normal



#### Startup: SAR

- Auto boot, load, and start SAR CSCI
  - COLDSTART:
    - Same as Normal state
  - NORMAL:
    - Start and initialize all CSCs.
    - Go to an idle state awaiting commands
  - RECOVERY:
    - Same as Normal state



#### Startup: DII/Workstation(s)

- Auto boot, load, and start DII CSCI
  - COLDSTART:
    - Operator must configure workstation using supplied DII tools, Security Manager & SysAdmin
    - Operator logs in as TCS System Maintenance user
      - Runs TCS Setup to configure TCS
  - NORMAL STARTUP:
    - Operator logs in as a TCS operator
      - Operator initiates TCS functions as required



#### CSCIs Startup Sequence

				CSCIs			
Seq	DCMs	RTP	DataServer	CAP	DII	RPP	SAR
StartUp	Auto	Auto	Auto		Auto/Manual		Manual
Auto Boot	OS loads	OS loads	OS loads		OS loads		OS loads
Auto Load	OS starts DCM Sw	OS starts RTP_Exec	OS starts DataServer		OS start DII		Manual Start
INIT	lnit	Init	Init		Init		Init
	Wait for RTP connect	Start CSC as per configuration	CSCs Init		DII starts segments		
		CSCs Init	Accept connections & Process Cmds				
	Connected	CSCs connect to device	Process Cmds				
	Report Status	Report status	"				
ldle	ldle	ldle	11				ldle



#### Operations State



#### Operations State

- All HWCIs & CSCIs are in a state ready to accept and process commands
  - Operational state consist of two substates
    - Normal Operations
      - State data indicates a startup after a normal system shutdown
    - Recovery
      - State data indicates that an operation was in progress and was not orderly terminated



#### Normal Operations State

• (SSS032)[SSDD285]

When in the Operations State the TCS Core Functionality CSCI shall provide a minimum of three modes: normal operations mode, training operations mode, and maintenance operations mode.

- Access to Normal Operations Mode shall be controlled by
  - DII Login/User Accounts
- Access to Training Operations Mode shall be controlled by
  - Designation of training missions

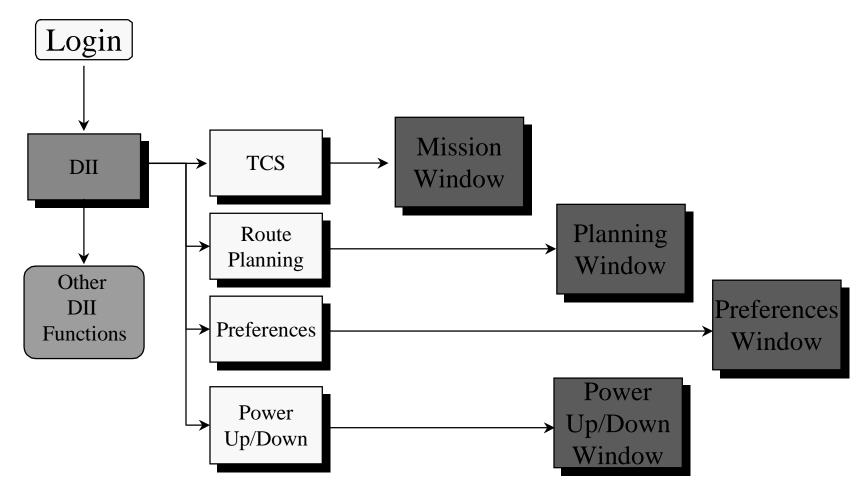


#### Normal Operations - Login Control

- Users will be classified as 1 of 3 types
  - TCS Operators: AVCs, AVOs, MPOs
    - User who is involved with the flight & control of a UAV and its payload(s)
  - TCS User: BFC, Client(s)
    - User who only monitors and/or processes data from a UAV
  - TCS Admin: System Maintenance
    - User who is involved with the configuration and setup of the system
- Their login account will be used to control access to TCS run time functionality

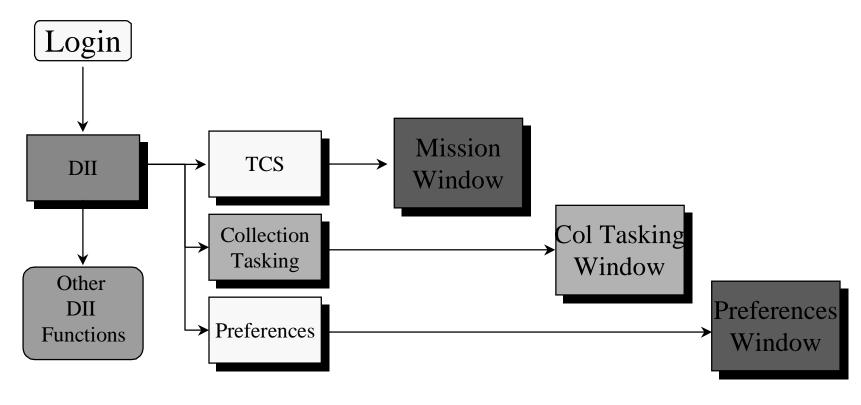


#### TCS Operator - Run Time Selections



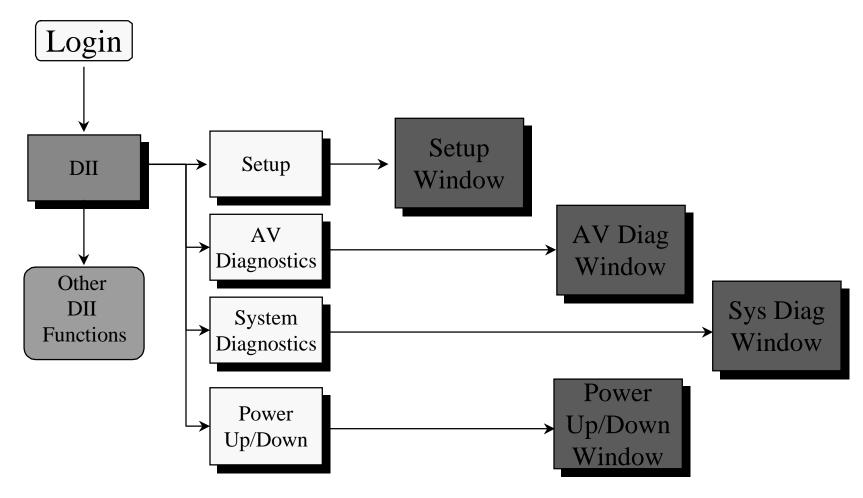


#### TCS User - Run Time Selections





#### TCS Admin - Run Time Selections





#### Recovery

• (SSS020)] [SSDD268]

When the TCS is halted due to an unplanned power interruption or abnormal program termination, TCS shall enter the Recovery Startup Mode upon the next startup cycle.

- Recovery is the responsibility of CAP CSCI
- All other CSCIs are "passive" with respect to the recovery process



#### Recovery: DII/Workstation(s)

- Operator restarts TCS
  - RECOVERY:
    - Workstation reboots
    - Operator logs in as TCS Operator or User
    - Re-selects previous running function/CSCI
    - Selected CSCI detects recovery state and begins recovery processing
    - Operator resumes operations



## CSCIs Operations Sequence

				CSCIs			
Seq	DCMs	RTP	DataServer	CAP	DII	RPP	SAR
Operations	Idle	Idle	Process Cmds		Opr logins		Opr logins
	II	"	"		Opr selects Task to Run		Opr starts SAR
	II	11	"		DII starts selected		Display Main
					function		Selection Window
START	II	"	"	DII starts TCS_Main		DII starts RPP	
	Process Cmds	Process Cmds	"	Init: Check role(s) and configuration		Init	
	11	"	"	Start required CSCs		Start required CSCs	
	11	"	"	Display Mission Window		Display Planning Window	
RUN	Process Cmds	Process Cmds	Process Cmds	Process Cmds	Process Cmds	Process Cmds	Process Cmds



## Mission Operations



#### Operations - Mission

- A distributive environment requires the communication of an "execution plan" to all participants
  - Who is responsible for what
  - When things are to happen
  - What needs to be done
  - What equipment is required
- These are the type of things covered in a "mission"
  - » Mission File will be the communication vehicle

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#### Mission File

- Mission File
  - Mission Purpose & Objectives
    - Mission overview or summary
    - Type of Mission; Operation, Exercise, or *Training*
    - Mission Execution Plan
      - Specifies required hardware resources
      - Operator/Workstation is performing which Role
      - Timeline, etc.
    - Collection Plan
  - AV & Payload Specs
    - Detailed data about AV & Payload
  - Datalink Plan
  - AV Route Data (Optional)
  - Payload Data (Optional)

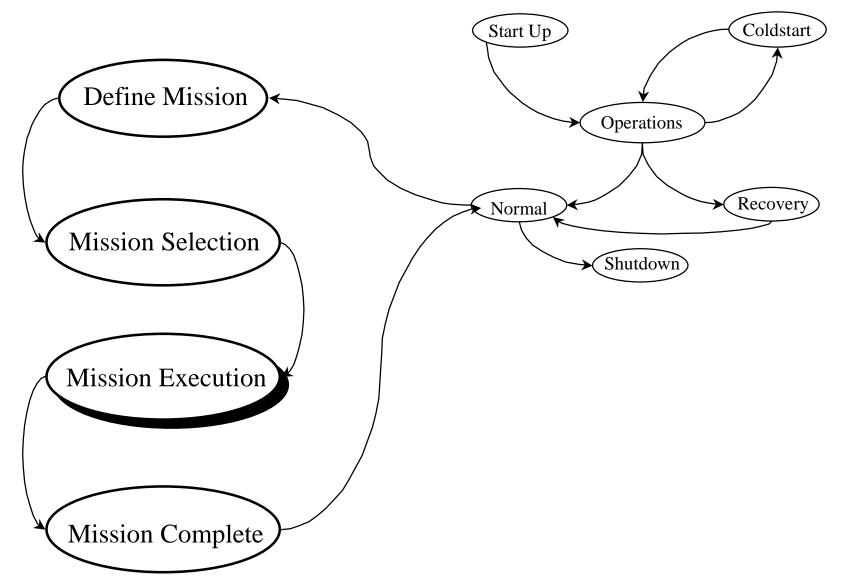


## Mission Operations State

- A mission is executed as a series of steps
  - 1) Define mission
  - 2) Select mission for execution
  - 3) Execute operations as required to complete mission
  - 4) Mission completed



## Mission Operations States





# Mission Operations <u>State 1</u>

- Mission Definition; AVC Role
  - Purpose of mission
    - Operation, Exercise, or *TRAINING*
  - Type of mission
  - Type of AV and type of payload
  - Builds route plan (Optional)
  - Identifies hardware asset required
  - Identifies operators for mission execution, AVO
     & MPO



## Mission Operations

#### State 2

- Mission Selection
  - IF TCS User; Client
    - Monitor mission
  - IF TCS Operator; AVO
    - AV Control and all required CSCs are started
    - AVO Worklist is displayed to begin AV Ops
  - IF TCS Operator; MPO
    - Payload Control and all required CSCs are started
    - MPO Worklist is displayed to begin Payload Ops



## Mission Operations State 3

- Mission Execution
  - IF TCS User; Client
    - Monitor mission
    - May run EO/IR Imagery Viewer & Capture
    - May run Imagery Processing & Data Extraction Tool
  - IF TCS Operator; AVO
    - Perform operations as required via AVO Worklist
  - IF TCS Operator; MPO
    - Perform operations as required vai MPO Worklist



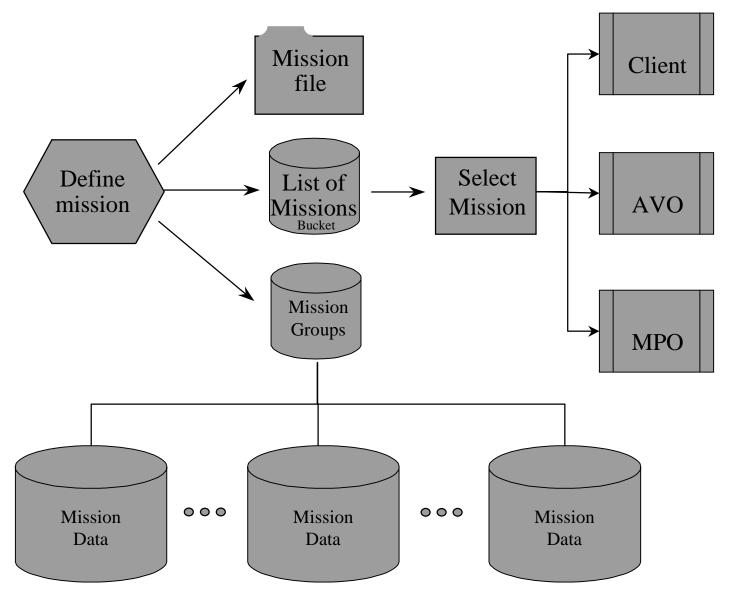
## Mission Operations

#### State 4

- Mission Complete
  - IF TCS User; Client
    - Exits TCS function when done
      - Can occur any time during mission
  - IF TCS Operator; AVO
    - Mission complete after Handoff-Give or Recovery of AV
  - IF TCS Operator; MPO
    - Mission complete when all data collected
    - Workstation remains online as backup for AVO



## Mission Flow





#### Mission List Bucket

- Mission List Bucket
  - Contains the List of Missions
    - Planned: Missions awaiting execution
    - Active: Missions being executed
- [Mission] Group
  - For each defined mission, a DataServer Group is created to hold the mission, AV specific data



#### Mission Data Buckets

- Mission Data Buckets
  - Mission Execution Plan
    - Specifies Required resources
    - Operator Workstations, AVO, MPO
    - Timeline, etc.
  - AV Data
    - Configuration, Autopilot Ver#, Capabilities (Day, D/Night, All Weather), Max Range, Max Flight Time, Payloads, etc.
    - Simplified Route Plan
    - AV & Payload Buckets
  - Datalink Data
    - RF Channels, Satcom, etc



## **SHUTDOWN**



#### Shutdown

• (SSS035)[SSDD286]

The TCS Core Functionality CSCI shall provide the operator, via the Work Station Console, with the capability to command the system to the shutdown state from all modes under the Operations State.

- Shutdown will be limited to TCS Operators and TCS Admins
  - AVC, AVO, MPO, & System Maintenance Roles
  - Shutdown will be designed to allow for the shutdown of all equipment or only selected equipment
  - Shutdown Order:
    - DCMs, RTP, DataServer, DII/Workstation
    - SAR may be shutdown when appropriate



## Shutdown: DCM(s)

- Operator initiates shutdown
  - CSCIs receives shutdown notice
    - Orderly termination of all running CSCs to ensure no loss or corruption of data
    - Responds with shutdown "ACK" before finial termination
  - Operator may power down unit



#### Shutdown: RTP

- RT
  - Operator initiates shutdown; AVC, AVO, TCS
     Admin
  - CSCI receives shutdown notice
    - Orderly termination of all running CSCs to ensure no loss or corruption of data
    - Responds with shutdown "ACK" before finial termination
      - Initiates OS Shutdown
  - Operator may power down unit



#### Shutdown: RTP

- DS
  - Operator initiates shutdown; AVC, AVO, TCS
     Admin
  - CSCI receives shutdown notice
    - Orderly termination of all running CSCs to ensure no loss or corruption of data
    - Responds with shutdown "ACK" before finial termination
    - Initiates OS Shutdown
  - Operator may power down unit



## Shutdown: DII/Workstation(s)

- Operator exits TCS functions
- Operator activates Shutdown via DII
  - Shutdown begins termination process
    - Operator may shutdown down all or selected unit
  - Log out
- TCS/DII Admin logs in
  - Operator initiates shutdown via DII functions
- Operator may power down workstation



#### Shutdown: SAR

- Operator exits TCS functions and logs out
  - Log in as Admin
    - Operator initiates shutdown via SGI functions
  - Operator may power down unit



## CSCIs Shutdown Sequence

				CSCIs			
Seq	DCMs	RTP	DataServer	CAP	DII	RPP	SAR
Shutdown	Idle	Id le	Idle	Opr exits	Opr selects	Opr exits	Opr exits
				function	Shutdown to	function	function
					Run		
					DII starts		Manual
					selected		shutdown via
					function		SGI cmds
				DII start TCS			Power down
				Setup(shutdown			
Shutdown	Process			Shutdown			
Command	Shutdown			Command			
	Terminate all	Process		Monitor			
	CSCs	Shutdown		shutdown			
	Shutdown ACK	Terminate all	Process Shutdown	"			
		CSCs					
	Idle	Shutdown ACK	Terminate all CSCs	"			
		Terminate OS	Shutdown ACK	"			
			Terminate OS				
	Idle	Id le	Idle	Exit function	Log out		
					Log in as Admin		
					Shutdown DII		
					Terminate all DII		
					Segments		
					Terminate OS		
	Idle	Idle	Idle	Idle	Id le	Idle	Idle
Power OFF	Power down	Power down	Power down	Power down	Power down	Power down	Power down



## Confirm SHUTDOWN now?